Dynamics and robustness of plant form

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What determines the trajectory in the space of shapes?

Outline

Average dynamics of leaf contours
From leaf contour to leaf blade

•Distributions of flower shape

Leaves in the model plant Arabidopsis thaliana



It is highly difficult to follow the same living leaf

samples 6th leaf



How to obtain a trajectory in shape space from independent samples?

Why leaves?

- Source of energy (photosynthesis)
- Diverse shapes: *simple, lobed, compound; toothed, untoothed*
- Shape ~ paleoclimates?



Greenwood, New Phytol 2005



Some of the previous approaches for leaves

Landmarks + PCA

Klingenberg J Evol Biol 2012



Discretised contour + PCA

Langlade et al. PNAS 2005





Fourier modes + PCA

Chitwood et al. Plant Physiol 2012



Little investigation of developmental trajectories

Combining landmarks and contours to analyse leaf morphogenesis

Collect a large number of samples (~300)



Identifying landmarks

- Basis, 2 points: expert
- Leaf tip: distance from basis
- Sinuses: curvature
- Tooth tips: curvature or symmetry





- Identifying primary sinuses: iterative tests based on angles (one parameter: limit angle)

Registration and reparametrisation

Contours $\mathbf{f}_i(s), i \in \{0, ..., n\}, s \in [0, s_{i,\omega}]$

Landmarks $\{s_{i,\alpha}\}, \alpha \in \{0, \ldots, \omega\}$ with $s_{i,0} = 0$

- Co-reparametrisation:

 $\varphi_i: [0, s_{i,\omega}] \to [0, 1]$ piecewise affine, such that $\varphi_i(s_{i,\alpha}) = \frac{\langle s_{i,\alpha} \rangle_i}{\langle s_{i,\omega} \rangle_i}$

Co-parametrised contours: $g_i = f_i \circ \varphi_i$

- Co-registration

Minimise the distance between contours modulo rotation-translation (R_i) and scaling (ρ_i): $\mathcal{E}(\{\rho_i, R_i\}) = \sum_{i > i} \int_0^1 d\tilde{s} \left(\rho_i R_i \mathbf{g}_i(\tilde{s}) - \rho_j R_j \mathbf{g}_j(\tilde{s})\right)^2$

solved through iterated Procustes transformations to an averaged contour

- Outcome:

Registered contours/landmarks $R_i f_i(s)$, to keep size information





Leaf tip vs. no landmark



Contours+ landmarks



Contours+ landmarks



Developmental trajectories



Developmental trajectories

n

Sliding average (Gaussian kernel) + quantification of leaf shape / teeth

Developmental trajectories



+ quantification of leaf shape / teeth



From leaf contours to leaf blade



Conformal maps: transformations that keep the same angles In 2D, the contours define all the transformation!

Applying conformal maps to leaves

Approach:

- Observe growing leaves
- Quantify contours and predict growth assuming conformal map (Schwartz-Christoffle)
- Quantify growth in the lamina
- Compare 'predicted' and measured growth









Good 'prediction' of displacements



Prediction of smoothed growth distribution

Robustness of form

Shape and size are robust in spite of internal and external perturbations



Bilateral symmetry

Shape and size are robust in spite of internal and external perturbations



Flower size in Arabidopsis varies by about 5%



Genetic screen for variability:

Individual plants in which sepals are variable in size

flowers from a single WT plant



flowers from the single vos l plant

Genetic screen for variability:

Individual plants in which sepals are variable in size



vos I mutant sepals



Towards a 3D analysis



- Image in 3D (confocal microscopy)
- •Binary images (supports) of many sepals
- Distance = overlap between supports
- Co-registration
- Probabilistic sepal

Summary

•Combining landmarks and contours to analyse leaf shape during morphogenesis

•Contours give all information for 2D isotropically growing systems

•Work in progress: variability of contours, 3D shape

Biot et al. Development 2016 Alim et al. Phys. Biol. 2016 Hong et al. Dev Cell 2016 Mollier et al. in progress